

Physics 541 – Important Formulas and Topics

Basic Mathematics

Divergence Theorem: $\oint_S \mathbf{A} \cdot d\mathbf{a} = \int_V (\nabla \cdot \mathbf{A}) d\tau$

Stokes' Theorem: $\oint_C \mathbf{A} \cdot d\mathbf{s} = \int_S (\nabla \wedge \mathbf{A}) \cdot d\mathbf{a}$

Gradient definition: $du = ds \cdot \nabla u$

Cylindrical co-ordinates: $r = \rho \hat{\rho} + z \hat{z}$; $\frac{\partial \hat{\rho}}{\partial \varphi} = \hat{\varphi}$; $\frac{\partial \hat{\varphi}}{\partial \varphi} = -\hat{\rho}$; $d\tau = d\rho \rho d\varphi dz$

$\hat{\rho} = \hat{x} \cos \varphi + \hat{y} \sin \varphi$; $\hat{\varphi} = -\hat{x} \sin \varphi + \hat{y} \cos \varphi$; $\hat{z} = \hat{z}$
 $\hat{x} = \hat{\rho} \cos \varphi - \hat{\varphi} \sin \varphi$; $\hat{y} = \hat{\rho} \sin \varphi + \hat{\varphi} \cos \varphi$; $\hat{z} = \hat{z}$

Spherical co-ordinates: $r = r \hat{r}$ $\frac{\partial \hat{r}}{\partial \theta} = \hat{\theta}$; $\frac{\partial \hat{r}}{\partial \varphi} = \hat{\varphi} \sin \theta$ $d\tau = dr r d\theta r \sin \theta d\varphi$
 $\frac{\partial \hat{\theta}}{\partial \theta} = -\hat{r}$; $\frac{\partial \hat{\theta}}{\partial \varphi} = \hat{\varphi} \cos \theta$
 $\frac{\partial \hat{\varphi}}{\partial \theta} = 0$; $\frac{\partial \hat{\varphi}}{\partial \varphi} = -\hat{r} \sin \theta + \hat{\theta} \cos \theta$

$\hat{r} = \hat{x} \sin \theta \cos \varphi + \hat{y} \sin \theta \sin \varphi + \hat{z} \cos \theta$; $\hat{\theta} = \hat{x} \cos \theta \cos \varphi + \hat{y} \cos \theta \sin \varphi - \hat{z} \sin \theta$; $\hat{\varphi} = -\hat{x} \sin \varphi + \hat{y} \cos \varphi$
 $\hat{x} = \hat{r} \sin \theta \cos \varphi + \hat{\theta} \cos \theta \cos \varphi - \hat{\varphi} \sin \varphi$; $\hat{y} = \hat{r} \sin \theta \sin \varphi + \hat{\theta} \cos \theta \sin \varphi + \hat{\varphi} \cos \varphi$; $\hat{z} = \hat{r} \cos \theta - \hat{\theta} \sin \theta$

Electrostatics

Coulomb: $\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{qq'}{R^2} \vec{R} = q \frac{1}{4\pi\epsilon_0} \int_V \vec{R} \frac{\rho(\vec{r}')}{R^2} d\tau'$; $\vec{F} = q\vec{E}$

Gauss: $\oint_S \vec{E} \cdot d\mathbf{a} = \sum q_{in} / \epsilon_0 = \int_V \rho / \epsilon_0 d\tau$; $\nabla \cdot \mathbf{E} = \rho / \epsilon_0$

Scalar Potential: $\phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho(\vec{r}')}{R} d\tau'$; $\vec{E} = -\vec{\nabla} \phi$

$$\Delta \phi = -\int_1^2 \vec{E} \cdot d\mathbf{s} \quad ; \quad \vec{\nabla} \wedge \vec{E} = 0 \quad ; \quad \oint_C \vec{E} \cdot d\mathbf{s} = 0$$

In electrostatics, $\mathbf{E} = 0$ in conductors

Electrostatic energy: $U = \frac{1}{2} \int_{all\ space} \rho(r)\phi(r) d\tau = \frac{1}{2} \int_{all\ space} \epsilon_0 E^2 d\tau = \frac{1}{2} \int_{all\ space} u_e d\tau$

Capacitors: $C = \frac{Q}{\Delta\phi}$ Parallel plate capacitor: $C = \frac{A\epsilon_0}{d}$

Energy stored in capacitors: $U = \frac{1}{2} C(\Delta\phi)^2 = \frac{Q^2}{2C} = \frac{1}{2} Q(\Delta\phi)$

Monopole moment: $Q_{mon} = \int_V \rho d\tau$ Dipole moment: $\vec{p} = \int_{V'} \rho(r') r' d\tau' = \sum_i q_i \vec{r}_i$

Dipole scalar potential: $\phi_{dip} = \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}$

Dipole in external E field: $U = -\vec{p} \cdot \vec{E}$ $\vec{\tau} = \vec{p} \wedge \vec{E}$

Boundary Conditions: $E_{1t} = E_{2t}$ $E_{2n} - E_{1n} = \sigma / \epsilon_0$ $\phi_1 = \phi_2$

Polarization: $d\mathbf{p} = \vec{P}(\vec{r})d\tau$ $\rho_b = -\nabla \cdot \vec{P}$ $\sigma = \vec{P} \cdot \hat{n}$
 ϕ due to \mathbf{P} is sum of ϕ given by ρ_b and σ_b

Displacement Field: $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$: b.c's
 $D_{2n} - D_{1n} = \sigma_f$ $D_{2t} - D_{1t} = P_{2t} - P_{1t}$

Gauss Law in dielectric media: $\nabla \cdot \vec{D} = \rho_f$

In l.i.h media $\vec{P} = \chi_e \epsilon_0 \vec{E}$ where $\chi_e = \kappa_e - 1$ $\epsilon = \epsilon_0 \kappa_e$

Effect of media on E, C, $\Delta\phi$ etc.

Energy in dielectrics (l.i.h): $u_e = \frac{1}{2} \mathbf{D} \cdot \mathbf{E} = \frac{1}{2} \epsilon E^2 = \frac{D^2}{2\epsilon}$

Current: $I = \frac{dq}{dt} = \int_S \mathbf{J} \cdot d\mathbf{a} = \int_C (\mathbf{K} \cdot \hat{t}) ds$

Current density: $\vec{J} = \rho \vec{v}$ $\vec{K} = \sigma \vec{v}$ $I = \lambda |\vec{v}|$

Current elements: $\vec{J} d\tau \equiv \vec{K} da \equiv \mathbf{I} ds \equiv q \vec{v}$ Conduction current: $\vec{J} = \sigma \vec{E}$

Equation of continuity: $\nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t}$

Resistance & Power: $\Delta\phi = IR$ $R = \frac{\rho \ell}{A}$ $Power = I^2 R$

Ampere's Law:
$$F_{CC'} = \frac{\mu_0}{4\pi} \oint_C \oint_{C'} \frac{I ds \wedge (I' ds' \wedge \hat{R})}{R^2} = \frac{-\mu_0 I I'}{4\pi} \oint_C \oint_{C'} \frac{(ds \cdot ds') \hat{R}}{R^2}$$

Definition of the Ampere

Biot-Savart Law:
$$\vec{B} = \frac{\mu_0}{4\pi} \oint_{C'} \frac{I' ds' \wedge \hat{R}}{R^2}$$
 so that
$$\vec{F} = \oint_C I ds \wedge \vec{B}$$

(similarly for surface and volume currents)

Ampere's Law Integral form:
$$\oint_C \vec{B} \cdot ds = \mu_0 I_{encl}$$
 Differential form:
$$\nabla \wedge \vec{B} = \mu_0 \vec{J}$$

No magnetic monopoles:
$$\nabla \cdot \vec{B} = 0$$

B b.c's:
$$B_{2t} - B_{1t} = \mu_0 (K \wedge \hat{n}) \quad B_{2n} - B_{1n} = 0$$

Vector Potential:
$$\vec{B} = \nabla \wedge \vec{A} \quad \vec{A} = \frac{\mu_0}{4\pi} \oint_{C'} \frac{I' ds'}{R}$$
 similarly for $J d\tau$, $K da$ and qv

$$\nabla \cdot \vec{A} = 0 \quad \nabla^2 \vec{A} = -\mu_0 \vec{J} \quad \vec{A} \text{ continuous}$$

$$\Phi_B = \int_S \vec{B} \cdot d\vec{a} = \oint_C \vec{A} \cdot ds$$

Gauge transformation
$$\vec{A} \rightarrow \vec{A} + \nabla \chi \quad \text{where } \nabla^2 \chi = 0$$

Faraday's Law:
$$\varepsilon_{ind} = -\frac{d\Phi_B}{dt} = \oint_C \vec{E}_{ind} \cdot ds \quad \nabla \wedge \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Mutual Induction:

$$M_{jk} = \frac{\mu_0}{4\pi} \oint_{C_j} \oint_{C_k} \frac{ds_j \cdot ds_k}{R_{jk}} \quad \varepsilon_j^{ind} = -\sum_k M_{jk} \frac{dI_k}{dt} \quad \Phi_j = \sum_k M_{jk} I_k$$

Self Induction:
$$L = \frac{\mu_0}{4\pi} \oint_j \oint_j \frac{ds_j \cdot ds_j}{R_{jj}} \quad \varepsilon_{ind} = -L \frac{dI}{dt} \quad \Phi_B = LI$$

Magnetic Energy:
$$U_B = \frac{1}{2} \sum_j \oint_{C_j} \vec{A}(r_j) \cdot ds_j I_j = \frac{1}{2} \int_V (\vec{J} \cdot \vec{A}) d\tau = \frac{1}{2} LI^2 = \int_V \frac{B^2}{2\mu_0} d\tau$$

Magnetic energy density:
$$u_B = \frac{B^2}{2\mu_0}$$

Magnetic forces on circuits:
$$\vec{F}_B = -\nabla U_B = -II' \nabla M$$

Magnetic Multipoles:
$$\vec{A} = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}}{R} d\tau = \vec{A}_{mon}(\vec{r}) + \vec{A}_{Dip}(\vec{r}) + \vec{A}_{Quad}(\vec{r}) + \dots$$

where,
$$\vec{A}_{Mon} = \frac{\mu_0}{4\pi r} \int_V \vec{J} d\tau' = 0 \quad A_{Dip} = \frac{\mu_0}{4\pi r^2} \int_V \vec{J}(\hat{r} \cdot \vec{r}') d\tau' = \frac{\mu_0}{4\pi r^2} (m \wedge \hat{r})$$

and magnetic dipole moment (filamentary currents):
$$\vec{m} = \frac{1}{2} \oint_C (\vec{r}' \wedge ds') I' \equiv I \vec{S}$$

Multipole field from
$$B = \nabla \wedge A$$

PE of mag dipole in external B field:
$$U_B = -\vec{m} \cdot \vec{B}_{ext}$$

Torque on magnetic dipole in external B field:
$$\vec{\tau} = \vec{m} \wedge \vec{B}_{ext}$$

Net force on magnetic dipole:
$$F = -\nabla U_B$$